

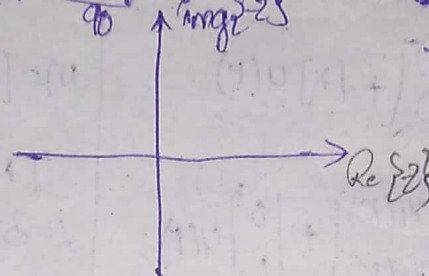
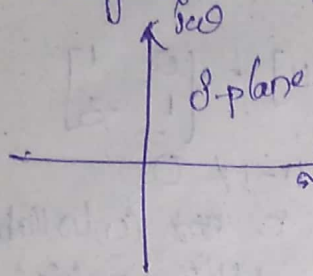
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UNIT-4

STABILITY ANALYSIS

Mapping b/w

s-plane & z-plane



+ve direction is 180, 270
+ve direction is 90, 0

Mathematical expression for $x(kT)$

$$x^*(s) = \sum_{k=0}^{\infty} x(kT) e^{-skT}$$

$$x(z) = \sum_{k=0}^{\infty} x(kT) z^{-k}$$

$$z = e^{sT}$$

$$= e^{(\sigma + j\omega)T} \quad (\because s = \sigma + j\omega)$$

$$= e^{\sigma T} + e^{j\omega T}$$

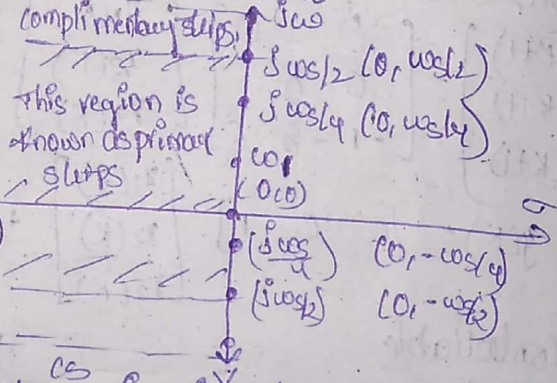
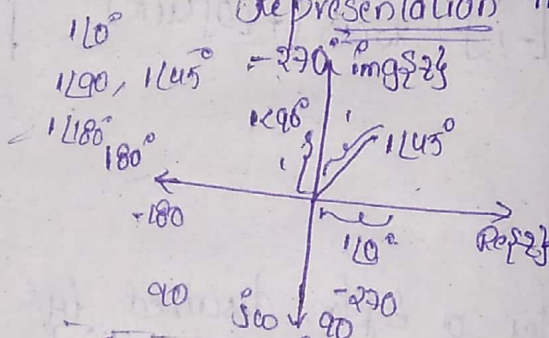
$$= e^{\sigma T} (\cos \omega T + j \sin \omega T)$$

$$z = e^{\sigma T} e^{j\omega T} \text{ (polar form)}$$

Mapping: $T = 2\pi / \omega$

$(0,0)$	$(0, \omega T/4)$	$(0, \omega T/2)$	$(0, -\omega T/4)$
$z = e^0$	$= e^{j\frac{\omega T}{4}}$	$= e^{j\frac{\omega T}{2}}$	$= e^{-j\frac{\omega T}{4}}$
$= 1 \angle 0^\circ$	$= e^{j\pi/2}$	$= e^{j\pi}$	$= e^{-j\pi/2}$
	$= 1 \angle 90^\circ$	$= -1 \angle 180^\circ$	$= 1 \angle 270^\circ$

Representation in polar form



* Relation b/w s-plane and z-plane is given by eqn $z = e^{sT}$

$$\therefore z = e^{\sigma T} e^{j\omega T}$$

Since $z = e^{j\omega T}$, the z varies from $-\infty$ to $+\infty$ as ω varies from $-\infty$ to ∞

Consider a representative pt on the $j\omega$ axis in s-plane. [is mapped into a radial line at const. angle $\omega T = T$ radians in z-plane as shown in fig] As this pt moves from $(-j\omega T/2)$ to $(+j\omega T/2)$ on the $j\omega$ -axis, we have magnitude of $z = 1$ ($|z| = 1$) & angle of z var. ($\angle z$ varies from $(-\pi)$ to (π) in the counter clockwise direction in z-plane. As the representative pt moves from $j\omega T/2$ to $j\omega T/2$ on $j\omega$ axis.

The corresponding pt in z-plane traces out the unit circle in the counter clockwise direction. Thus, as pt in s-plane moves from $-\infty$ to ∞ on the $j\omega$ axis, the unit circle in z-plane an infinite no. of times.

from this analysis it is clear that each strip of width ω in the left half of s-plane maps into inside of unit circle in z-plane.

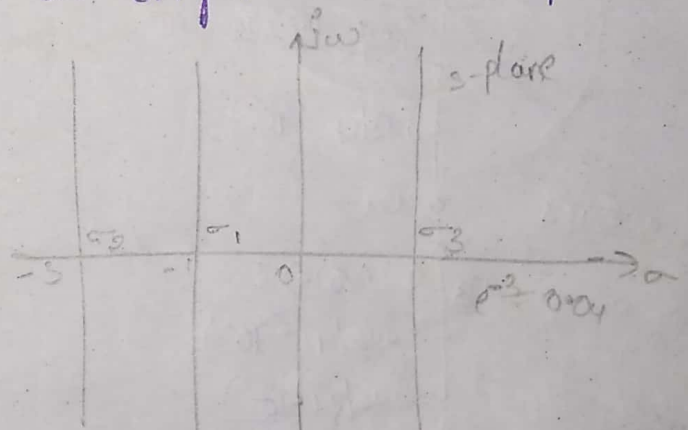
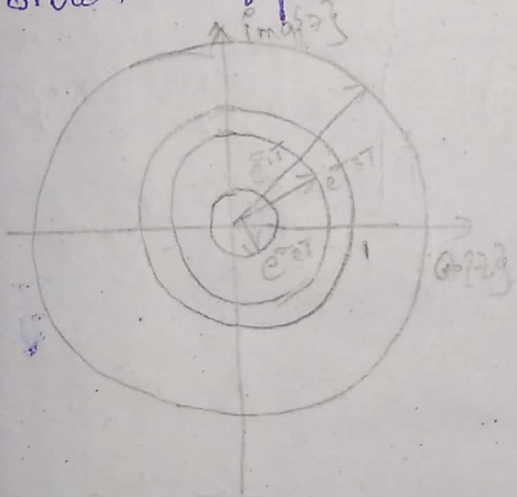
This implies that the left half of the s-plane may be divided into an infinite no. of periodic strips as shown

in the fig.

→ The primary strip extends from $\sigma = -\frac{\omega}{2}$ to $+\frac{\omega}{2}$

→ The complementary strips extends from $\frac{\omega}{2}$ to $\frac{3\omega}{2}$, $\frac{5\omega}{2}$ to $\frac{7\omega}{2}$, $-\frac{\omega}{2}$ to $-\frac{3\omega}{2}$, $-\frac{5\omega}{2}$ to $-\frac{7\omega}{2}$ and so on...

Constant attenuation line :- A constant attenuation line is plotted as $\sigma = \text{constant}$ in the s-plane. Maps to a circle of radius i.e., $z = e^{-\sigma T}$ centered at origin in the z-plane as shown in fig.



$$e^{-(\sigma + j\omega)T} = e^{-\sigma T} e^{-j\omega T} = e^{-\sigma T} \angle -\omega T$$

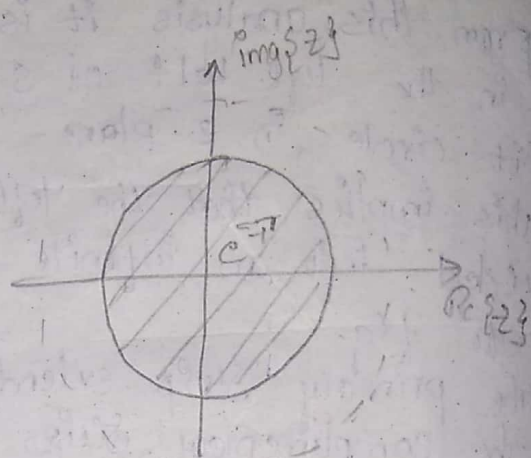
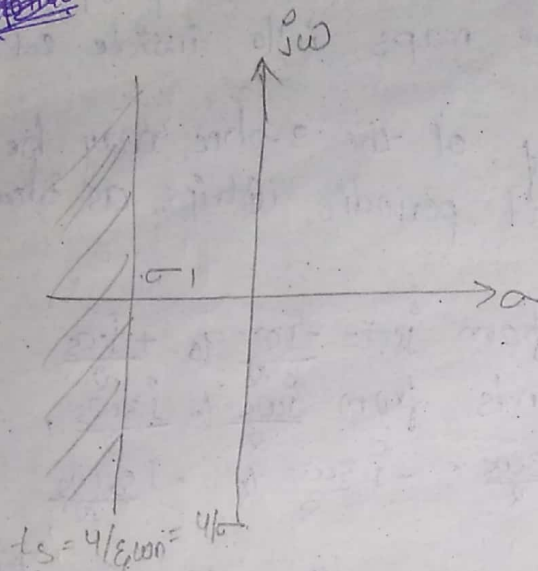
$$\text{let } T = 1 \text{ sec}$$

$$e^{-1} = 0.3679$$

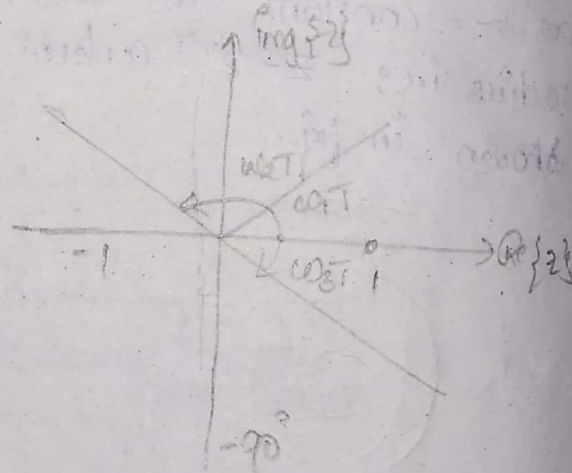
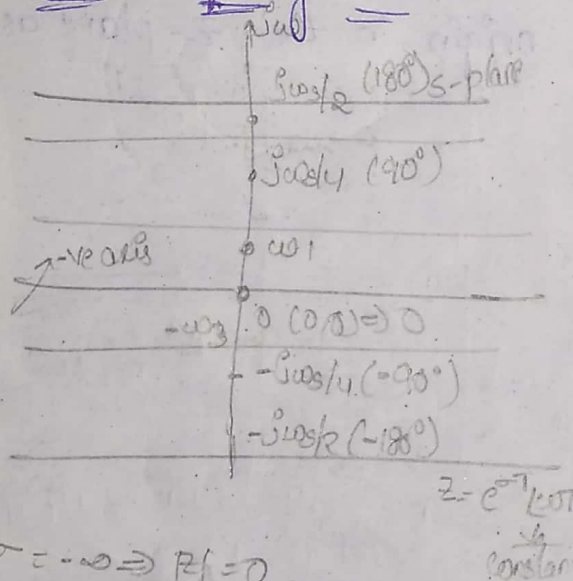
Settling Time (T_s) :- The settling time (T_s) is determined by the value of attenuation σ of the dominant closed loop poles. If the settling time is specified, it is possible to draw a line $\sigma = -\sigma_1$ in the s-plane corresponding to a given settling time.

The region to the left of the line $\sigma = -\sigma_1$ in the s-plane corresponds to the inside of circle with radius $e^{-\sigma_1 T}$ in the z-plane as shown in the fig.

~~Chapter~~



Constant frequency locus:-



$$\sigma = -\infty \Rightarrow |z| = 0$$

$$\sigma = 0 \Rightarrow |z| = 1$$

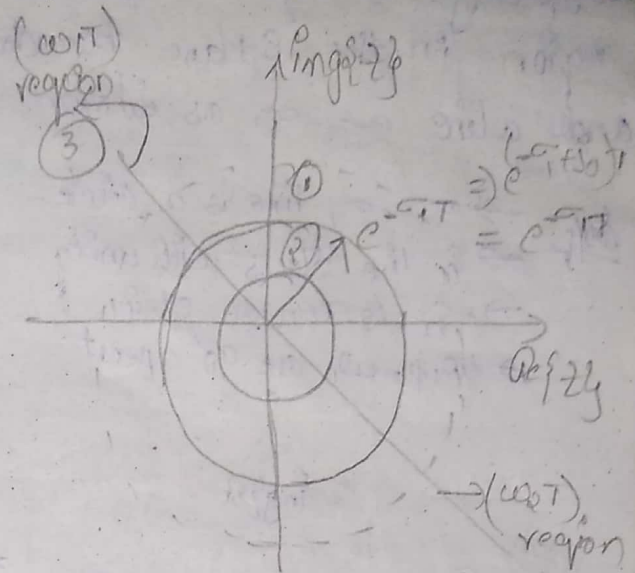
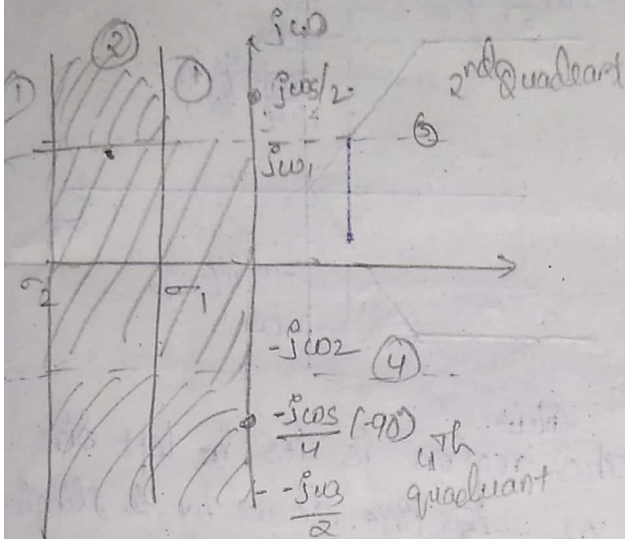
$$\sigma = \infty \Rightarrow |z| = \infty$$

A constant freq. locus $\omega = \omega_1$ in the s-plane is mapped into a radial line of constant angle $\omega_1 T$ radius in the z-plane as shown in fig.

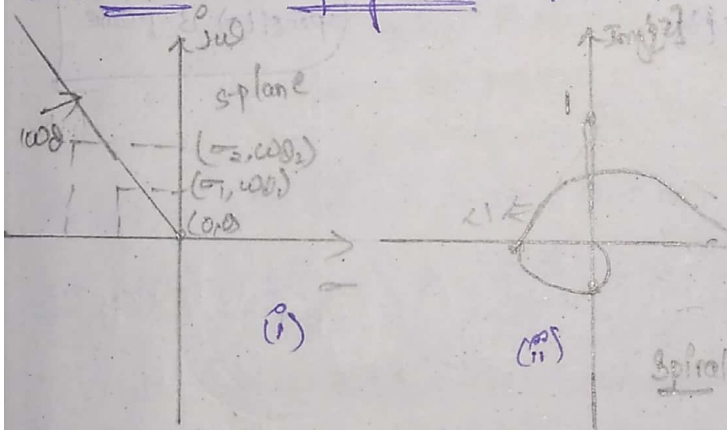
Note:- the constant freq. line $\omega = \pm \omega_3/2$ in the left half of s-plane corresponds to the -ve real axis in the z-plane b/w 0 & -1. Since $\angle T(\pm \omega_3/2) = \pm \pi$ radians.

constant freq. lines at $\omega = \pm \omega$ in the right half of the s-plane corresponds to the -ve real axis in the z-plane b/w -1 and $-\infty$

Sol.



* Constant damping ratio: (ξ)



$$z = \sqrt{f \cos \theta + g \cos \sqrt{1-f^2}} \pi$$

$$= \rho (E_{\text{cont}} + S_{\text{cont}} \sqrt{1 - \epsilon^2})$$

$$Z = C \frac{\omega L + \frac{R}{\omega C}}{\sqrt{1 - \epsilon^2} \omega} = \frac{C \omega L + \frac{R}{C}}{\sqrt{1 - \epsilon^2} \omega}$$

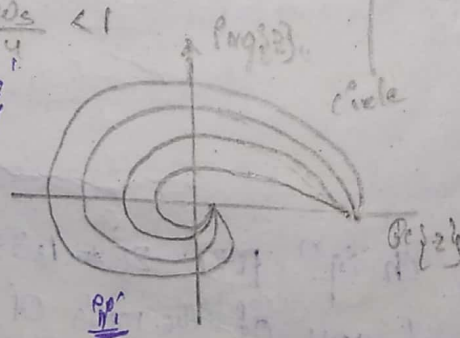
$$E = \text{constant}$$

2. yone is a verb word (verb)

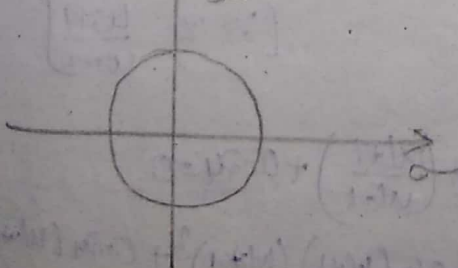
S-Plane
 $f(0) \Rightarrow e^{0 \cdot j\omega} = e^0 = 1/0$

$$P_1(\sigma_1, \omega_1) \Rightarrow \sigma_1 = \frac{\omega_1}{4} < 1$$

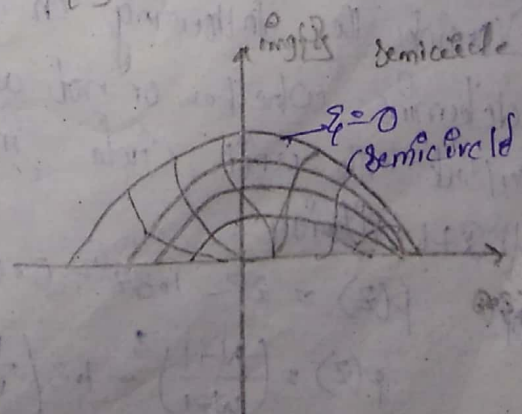
for diff values of ϵ



* constant con 1-

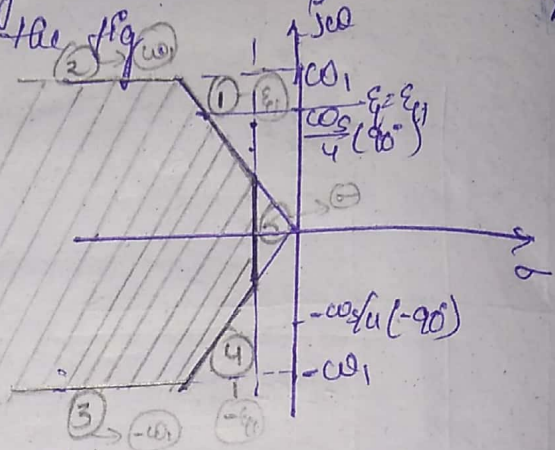


$$\begin{aligned} &0.2 \left(\frac{\text{cal}}{2} \right) \\ &0.4 \left(\frac{\text{cal}}{2} \right) \\ &0.8 \left(\frac{\text{cal}}{2} \right) \\ &1 \left(\frac{\text{cal}}{2} \right) \end{aligned}$$



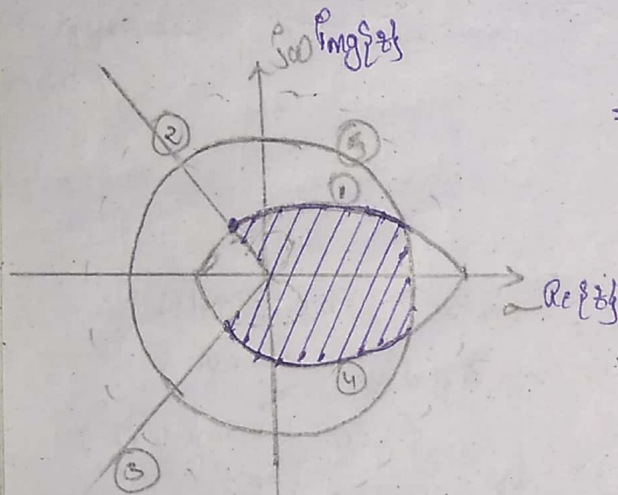
* Specify the region in z -plane that corresponds to a desirable region in the s -plane bounded by the line $\omega = \pm \omega_1$, lines $\xi = \xi_1$ and a line $\sigma = -\sigma_1$ as shown in the fig.

- $\rightarrow \sigma = -\sigma_1$ line is a circle.
 $\rightarrow \xi_1$ line starts with unity
 $\rightarrow -\xi_1$ is reverse of ξ_1
 $\rightarrow \omega_1, \phi - \omega_1$ are 90° apart



The region lies to the left side of $-\sigma_1$ line. So we have to eliminate σ_1, σ_1 lines.

blue pen $\rightarrow z$ -plane
 pencil $\rightarrow s$ -plane



* Modified R-H Criteria:-

$\rightarrow$ No. of sign changes represents no. of poles present in R.H.S.

We can apply RH for z -plane. So we have to convert z -plane $\rightarrow s$ -plane.

"w-plane" z -plane $\rightarrow w$ -plane
 "bilinear transformation"

$$z = \frac{w+1}{w-1}$$

$$a_n s^n + a_{n-1} s^{n-1} + a_{n-2} s^{n-2} + \dots + a_0 = 0 \rightarrow \text{ch's eqn}$$

RH criterion

$$\begin{array}{ccc}
 a_0 & a_2 & a_4 \\
 a_1 & a_3 & a_5 \\
 \hline
 \frac{a_2 - a_0 a_1}{a_1} & \frac{a_4 - a_2 a_1}{a_1} & B \\
 \hline
 \frac{a_3 - B a_1}{A} & &
 \end{array}$$

Ques

Consider the following ch eqn $P(z) = z^3 - 1.3z^2 - 0.08z + 0.24 = 0$
 determine whether or not any of the roots of ch's eqn of line outside the unit circle in the z -plane. Use bilinear transformation & R-H criterion.

$$\because z = \frac{w+1}{w-1}$$

$$P(z) = z^3 - 1.3z^2 - 0.08z + 0.24$$

$$P(z) = \left(\frac{w+1}{w-1}\right)^3 - 1.3\left(\frac{w+1}{w-1}\right)^2 - 0.08\left(\frac{w+1}{w-1}\right) + 0.24 = 0$$

$$(w+1)^3 - 1.3(w+1)^2(w-1) - 0.08(w+1)(w-1)^2 + 0.24(w-1)^3 = 0$$

$$w^3 + 1 + 3w^2 + 3w - 1.3(w^2 + 1 + 2w)(w-1) - 0.08(w+1)(w^2 - 1 - 2w) = 0$$

$$+0.24(\omega^3 + 1 - 3\omega^2 + 3\omega) = 0$$

$$\omega^3 + 3\omega^2 + 3\omega + 1 - 1.3(\omega^3 + \omega + 2\omega^2 - \omega^2 - 1 - 2\omega) - 0.08(\omega^3 + \omega - 2\omega^2 + \omega^2 + 1 - 2\omega) + 0.24(\omega^3 - 3\omega^2 + 3\omega - 1) = 0$$

$$\omega^3(1 - 1.3 - 0.08 + 0.24) + \omega^2(3 - 1.3 - 1.3 - 0.24) + \omega(3 + 1.3 + 0.08 + 0.72) + 1 + 1.3 - 0.08 - 0.24 = 0$$

$$\boxed{-0.14\omega^3 + 1.06\omega^2 + 5.1\omega + 1.98 = 0} \Rightarrow \text{Ch's eqn}$$

→ 1 sign change is there
do one pole is present
outside the unit circle.
therefore the system is unstable

sign change	-	-0.14	5.1	
	+	1.06	1.98	
	+	$\frac{(1.06)(5.1) - (-0.14 \times 1.98)}{1.06} = 5.36$		0
	+	1.98		

Note:
→ If we get any 0 value replace it as 'ε' and continue the process. At last equal that eqn to 0
→ If any row is entirely 0, then take aux. eqn

⑥ $p(z) = z^3 - 1.1z^2 - 0.1z + 0.2 = 0$

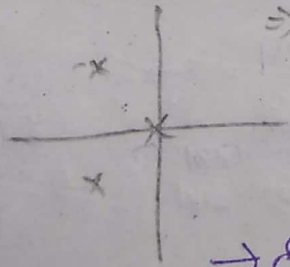
Sol: $p(z) = \left(\frac{w+1}{w-1}\right)^3 - 1.1\left(\frac{w+1}{w-1}\right)^2 - 0.1\left(\frac{w+1}{w-1}\right) + 0.2 = 0$

$$(w+1)^3 - 1.1(w+1)^2(w-1) - 0.1(w+1)(w-1)^2 + 0.2(w-1)^3 = 0$$

$$w^3 + 3w^2 + 3w + 1 - 1.1(w^3 + w^2 - w - 1) - 0.1(w^3 - w^2 - w + 1) + 0.2(w^3 - 3w^2 + 3w - 1) = 0$$

$$w^3(1 - 1.1 - 0.1 + 0.2) + w^2(3 - 1.1 + 0.1 - 0.6) + w(3 + 1.1 + 0.1 + 0.6) + 1 + 1.1 - 0.1 - 0.2 = 0$$

$$1.4w^2 + 4.8w + 1.8 = 0 \Rightarrow \text{Ch's eqn}$$



→ No sign change
so, pole are in
LHS, another
pole at origin

	-	1.4	1.8
	+	4.8	0
		1.8	

→ So, system is marginally stable / critically stable

Q1100 (3) check whether or not all the poles of chs z^n lies inside the unity circle or not. $5z^2 - 2z + 2 = 0$

Soln $5\left(\frac{w+1}{w-1}\right)^2 - 2\left(\frac{w+1}{w-1}\right) + 2 = 0$

$$5(w^2 + 2w + 1) - 2(w^2 - 1) + 2(w^2 - 2w + 1) = 0$$

$$5w^2 + 10w + 5 - 2w^2 + 2 + 2w^2 - 4w + 2 = 0$$

$$5w^2 + 6w + 9 = 0$$

There are no sign changes in 1st column of RH table.

5	9
6	0
$\frac{5 \times 9}{6} = 9$	

column of RH table.

→ There are zero poles lies lies to RH of w-plane

→ All poles are lies inside the unit circle of z-plane. So, the system is "stable"

(4) $z^3 - 0.2z^2 - 0.25z + 0.05 = 0$

Soln $\left(\frac{w+1}{w-1}\right)^3 - 0.2\left(\frac{w+1}{w-1}\right)^2 - 0.25\left(\frac{w+1}{w-1}\right) + 0.05 = 0$

$$w^3 + 1 + 3w^2 + 3w - 0.2(w^2 + 1 + 2w)(w-1) - 0.25(w+1)(w^2 - 2w + 1) + 0.05(w^3 - 1 - 3w^2 + 3w) = 0$$

$$w^3 + 1 + 3w^2 + 3w - 0.2(w^3 - w^2 + w - 1 + 2w^2 - 2w) - 0.25(w^3 - 2w^2 + w) + 0.05w^3 - 0.05 - 0.15w^2 + 0.15w = 0$$

$$0.6w^3 + 2.9w^2 + 3.6w + 0.9 = 0$$

→ NO sign changes, no pole

is outside the circle so system

is stable.

0.6	3.6
2.9	0.9
$\frac{(2.9 \times 3.6) - (0.6 \times 0.9)}{3.6}$	$\frac{2.9 \times 0.9}{3.6}$
2.9	0.7
0.9	

(5) $z^4 - 1.7z^3 + 1.04z^2 - 0.268z + 0.024 = 0$

Soln $\left(\frac{w+1}{w-1}\right)^4 - 1.7\left(\frac{w+1}{w-1}\right)^3 + 1.04\left(\frac{w+1}{w-1}\right)^2 - 0.268\left(\frac{w+1}{w-1}\right) + 0.024 = 0$

$$(w+1)^2(w+1)^2 - 1.7(w+1)^3(w-1) + 1.04(w+1)^2(w-1)^2 - 0.268(w+1)(w-1)^3 + 0.024(w-1)^2(w-1) = 0$$

$$w^4 + 4w^3 + 6w^2 + 4w + 1 - 1.7(w-1)(w^3 + 3w^2 + 3w + 1) + 1.04(w^2 + 1 + 2w) \\ (w^2 - 2w + 1) - 0.268(w+1)(w^3 - 3w^2 + 3w - 1) + 0.024(w^4 + 4w^3 + 6w^2 + 4w + 1)$$

$$w^4 + 4w^3 + 6w^2 + 4w + 1 - 1.7(w^4 + 3w^3 + 3w^2 + w - w^3 - 3w^2 - 3w - 1) \\ + 1.04(w^4 - 2w^3 + w^2 + w^2 - 2w + 1 + 2w^3 - 4w^2 + 2w) - 0.268 \\ (w^4 - 3w^3 + 3w^2 - w + w^3 - 3w^2 + 3w - 1) + 0.024(w^4 + 4w^3 + 6w^2 + 4w + 1) =$$

$$w^4(1 - 1.7 + 1.04 - 0.268 + 0.024) + w^3(4 + 3.4 + 0.536 - 0.024) \\ + w^2(6 - (2 \times 1.04) + (0.024 \times 6)) + 1 + 1.7 + 4 \times 0.268 + 0.024 = 0$$

$$0.096w^4 + 1.04w^3 + 4.064w^2 + 7.968w + 4.03 = 0$$

$$0.096w^4 + 1.04w^3 + 4.064w^2 + 7.968w + 4.03 = 0$$

no sign changes,
system is stable

0.096	4.064	4.03
1.04	7.168	0
3.56	4.03	
5.99		

6) Find cond'n on 'm' such that the given system is stable

$$z^3 + mz^2 + 3mz + (m-2) = 0$$

$$\text{Subst } \left(\frac{w+1}{w-1} \right)^3 + m \left(\frac{w+1}{w-1} \right)^2 + 3m \left(\frac{w+1}{w-1} \right) + m-2 = 0$$

$$w^3 + 3w^2 + 3w + 1 + m(w^3 + w^2 - w - 1) + 3m(w^3 - w^2 - w + 1) + \\ (m-2)(w^3 - 3w^2 + 3w - 1) = 0$$

$$w^3(1 + m + 3m + m - 2) + w^2(3 + m - 3m - 3m + 6) + w(3 - m - 3m \\ + 3m - 6) + 1 - m + 3m - m + 2 = 0$$

$$(5m-1)w^3 + (9-5m)w^2 - w(3+m) + m+3 = 0$$

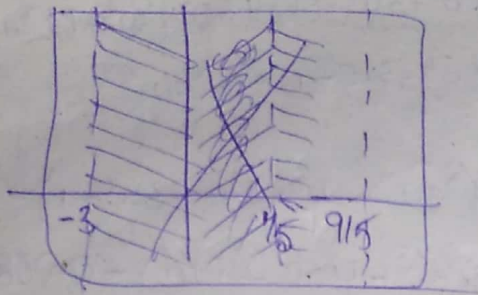
$$\text{Cond'n } 5m-1 > 0 \Rightarrow m > 1/5$$

$$9-5m > 0 \Rightarrow m < 9/5$$

$$3+m > 0 \Rightarrow m > -3$$

$$-8m-24/9-5m > 0 \Rightarrow -8m-24 > 0 \Rightarrow m < -3$$

5m-1	-3-m
9-5m	m+3
-8m-24	
9-5m	
m+3	



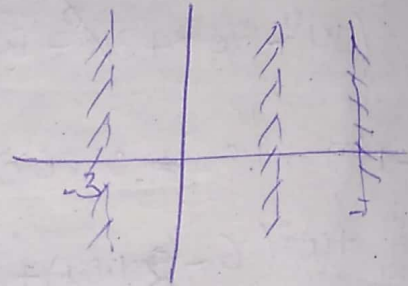
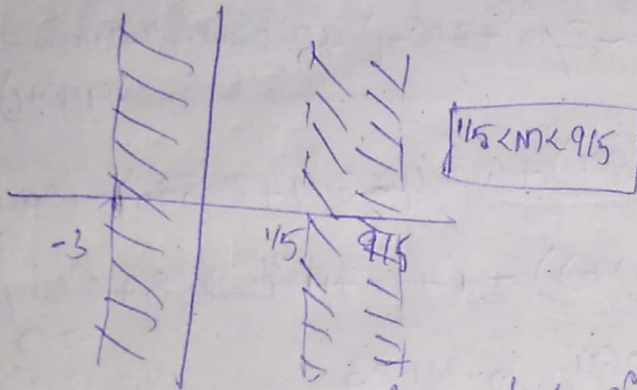
Case-II

$$5M - 1 < 0 \Rightarrow M < 1/5$$

$$9 - 5M < 0 \Rightarrow M > 9/5$$

$$3 + M < 0 \Rightarrow M < -3$$

$$8M + 24 < 0 \Rightarrow M < -3$$



Q. Find range of k for which given system is stable, given, Pds
T.O.F of a open loop unity feedback control sys. with sampling
time period $T=1s$ $F(z) = \frac{K(0.3679z + 0.2642)}{(z - 0.3679)(z - 1)}$

Soln

$$1 + F(z)H(z) = 0$$

$$[\because H(z) = 1]$$

$$1 + \frac{K(0.3679z + 0.2642)}{(z - 0.3679)(z - 1)} = 0$$

$$(z - 0.3679)(z - 1) + K(0.3679z + 0.2642) = 0$$

$$z^2 - 1.3679z + 0.3679 + K(0.3679z + 0.2642) = 0$$

$$z^2 + z(0.3679K - 1.3679) + 0.2642K + 0.3679 = 0$$

$$0 < K < 2.3925$$

$$z = \frac{w+1}{w-1}$$

$$(w^2 + 2w + 1) + (0.3679K - 1.3679)(w^2 - 1) + (0.2642K + 0.3679) = 0$$

$$0.3679Kw^2 - 1.3679w^2 - 0.3679K + 1.3679 + 0.2642Kw + 0.2642 = 0$$

$$w^2(1 + 0.3679K)$$

$$w^2 + 2w + 1 + 0.3679Kw^2 - 0.3679K - 1.3679w^2 + 1.3679 + 0.2642Kw - 0.2642 = 0$$

$$w^2(1 + 0.3679K - 1.3679 + 0.3679 + 0.2642K) +$$

$$w(2 - 0.7358 - 0.5284K) + (1 - 0.3679K + 1.3679 + 0.3679 + 0.2642K) = 0$$

$$0.6321Kw^2 + (1.2642 - 0.5284K)w + 2.7358 - 0.1037K = 0$$

conds

$$0.6321K > 0 \Rightarrow K > 0$$

$$1.2642 - 0.5284K > 0 \Rightarrow K < 2.39$$

$$2.7358 - 0.1037K > 0$$

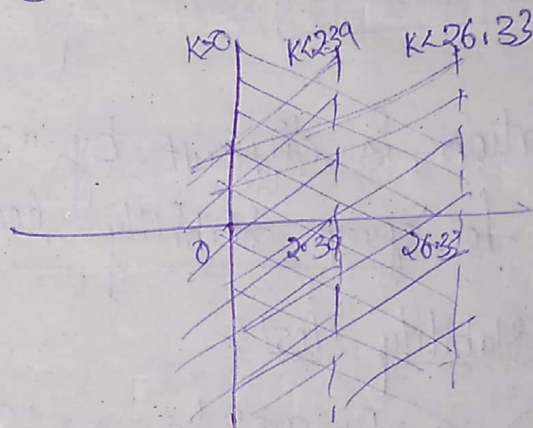
$$\Rightarrow K < 26.33$$

$$0 < K < 2.39$$

$$0 < K < 2.39$$

$$0.6321K \quad 2.7358 - 0.1037K$$

$$1.2642 - 0.5284K \quad 0$$



soln

$$f(z) = \frac{K(z-1)}{(z-0.1)(z-0.8)}$$

$$1 + f(z)H(z) = 0$$

$$1 + \frac{K(z-1)}{(z-0.1)(z-0.8)} = 0$$

$$(z-0.1)(z-0.8) + K(z-1) = 0$$

$$z^2 - 0.9z + 0.08 + Kz - K = 0$$

$$z^2 + z(-0.9 + K) + 0.08 - K = 0$$

$$(w^2 + 2w + 1) + (-0.9 + K)(w^2 - 1) + (0.08 - K)(w^2 - 2w + 1) = 0$$

$$w^2 + 2w + 1 - 0.9w^2 + 0.9 + Kw^2 - K + 0.08w^2 - 0.16w + 0.08 - Kw^2 + 2Kw - K = 0$$

$$w^2(1 - 0.9 + K + 0.08 - K) + w(2 - 0.16 + 2K) + (1 + 0.9 - K + 0.08 - K) = 0$$

$$0.18w^2 + (1.84 + 2K)w + (1.98 - 2K) = 0$$

Condns

$$1.98 - 2K > 0$$

$$\Rightarrow 2K < 1.98$$

$$K < 0.99$$

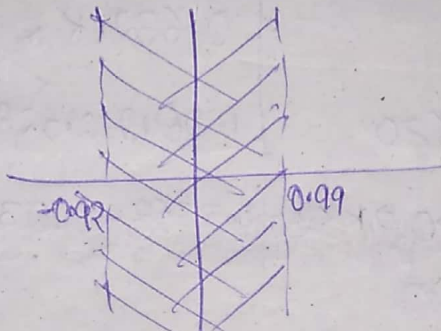
$$1.84 + 2K > 0$$

$$2K > -1.84$$

$$K > -0.92$$

$$\boxed{-0.92 < K < 0.99}$$

$$\begin{cases} 0.18 \\ 1.84 + 2K \\ 1.98 - 2K \end{cases}$$



* calculation is difficult by using this method then we go for Jury stability test

* Jury stability test:-

$$P(z) = a_0 z^n + a_1 z^{n-1} + \dots + a_n = 0$$

$$1. |a_n| < |a_0|$$

$$2. P(z)|_{z=1} > 0$$

$$3. \lim_{z \rightarrow \infty} P(z) > 0 \quad n = \text{even}$$

$$z = -1 < 0 \quad n = \text{odd}$$

$$4. |b_{n-1}| > |b_0|$$

$$|c_{n-2}| > |c_0|$$

for all

$$q_2 > q_0$$

$$b_{n-1} = \begin{vmatrix} a_n & a_0 \\ a_0 & a_n \end{vmatrix}; b_{n-2} = \begin{vmatrix} a_n & a_1 \\ a_0 & a_{n-1} \end{vmatrix}; b_0 = \begin{vmatrix} a_n & a_{n-1} \\ a_0 & a_1 \end{vmatrix}$$

$$1. P(z) = z^3 + 1.3z^2 - 0.08z + 0.24 = 0$$

$$\begin{matrix} 0.24 & -0.08 & -1.3 & 1 \\ 1 & -1.3 & -0.08 & 0.24 \end{matrix}$$

$$\begin{matrix} (0.24)(0.24) - (1)(-0.08) & (0.24)(-0.08) - (1)(-1.3) & (0.24)(-1.3) + 0.08 \\ = -0.94 & = 1.28 & = -0.28 \end{matrix}$$

$$i \quad 0.24 < 1 \quad (\text{True})$$

$$ii \quad 1 - 1.3 - 0.08 + 0.24 = -0.14 < 0 \quad (\text{false})$$

$\therefore$ System is unstable.

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$$① \quad P(z) = z^3 - 1.1z^2 - 0.1z + 0.2 = 0$$

$$i \quad |a_n| < a_0$$

$$0.2 < 1 \quad (\text{True})$$

$$ii \quad P(z)/z=1 \Rightarrow 1 - 1.1 - 0.1 + 0.2$$

$$0 > 0 \quad (\text{Not Satisfied})$$

$\downarrow$ marginally stable (bc it is 0)
 $\downarrow$ < 0 means unstable
 we hv to check another condⁿ

0.2	-0.1	-1.1	1
1	-1.1	-0.1	0.2
$(0.2)(0.2) - 1$	$(0.2)(-0.1) + 1.1$	$(0.2)(-1.1) + 0.1$	
$= -0.96$	$= 1.88$	$= -0.12$	

$$iii \quad P(z)/z=-1 \Rightarrow -1 - 1.1 + 0.1 + 0.2 = -1.8 < 0 \quad (\text{True})$$

$$iv \quad |b_{n-1}| > |b_0| \Rightarrow 0.96 > 0.12 \quad (\text{True})$$

$\therefore$ System is marginally stable.

$$③ \quad 5z^2 - 2z + 2$$

$$i \quad |a_n| < |a_0| \Rightarrow 2 < 5 \quad (\text{True})$$

$$ii \quad P(z)/z=1 \Rightarrow 5 - 2 + 2 = 5 > 0 \quad (\text{True})$$

$$iii \quad P(z)/z=-1 \Rightarrow 5 + 2 + 2 = 9 > 0 \quad (\text{True})$$

$\therefore$ System is stable

$$④ \quad z^3 - 0.2z^2 - 0.25z + 0.05$$

$$i \quad |a_n| < |a_0| = 0.05 < 1 \quad (\text{True})$$

$$ii \quad P(z)/z=1 = 1 - 0.2 - 0.25 + 0.05$$

$$= 0.6 > 0 \quad (\text{True})$$

$$iii \quad P(z)/z=-1 = -1 - 0.2 + 0.25 + 0.05$$

$$= -0.9 < 0 \quad (\text{True})$$

$$|b_{n-1}| > |b_0| \Rightarrow |b_2| > |b_0| \Rightarrow 0.99 > 0.05 \quad (\text{True})$$

$\therefore$ System is stable.

0.05	-0.25	-0.2	1
1	-0.2	-0.25	0.05
$(0.05)(0.05) - 1$	$(0.05)(-0.25)$	$(0.05)(-0.2)$	
$= -0.99$	$+ 0.0125$	$+ 0.01$	
	$= 0.187$	$= 0.04$	

$$(5) z^3 + Mz^2 + 3Mz + (M-2) = 0$$

$$\text{for } |a_n| < |a_0| \Rightarrow M-2 < 1 \Rightarrow \boxed{M < 3}$$

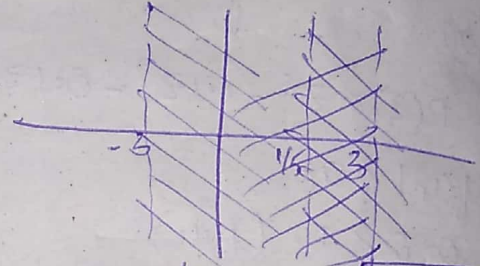
$$\begin{aligned} \text{ii } P(z)|_{z=1} &= 1+M+3M+M-2 \\ &= 5M-1 > 0 \Rightarrow \boxed{M > 1/5} \end{aligned}$$

$$\begin{aligned} \text{iii } P(z)|_{z=-1} &= -1+M-3M+M-2 \\ &= -M-3 < 0 \Rightarrow \boxed{M > -3} \end{aligned}$$

$$\text{iv } |b_{n-1}| > |b_0| \Rightarrow |b_2| > |b_0| \Rightarrow M^2 - 4M + 3 > M^2 - 5M \Rightarrow \boxed{M > -3}$$

$$\begin{array}{cccc} M-2 & 3M & M & 1 \\ 1 & M & 3M & M-2 \\ (M-2)^2 - 1 & 3M^2 - 7M & M^2 - 5M & \end{array}$$

$$= M^2 - 4M + 3$$



$$(6) P(z) = \frac{K(0.3679z + 0.2642)}{(z - 0.3679)(z - 1)}$$

$$C.E \Rightarrow 1 + P(z)H(z) = 0$$

$$1 + F(z) = 0$$

$$1 + \frac{K(z)}{(z)(z)} = 0$$

$$(z - 0.3679)(z - 1) + K(0.3679z + 0.2642) = 0$$

$$z^2 - 1.3679z + 0.3679 + K(z) = 0$$

$$z^2 + z(-1.3679 + 0.3679K) + (0.3679 + 0.2642K) = 0$$

$$\text{ii } |a_1| < |a_0|$$

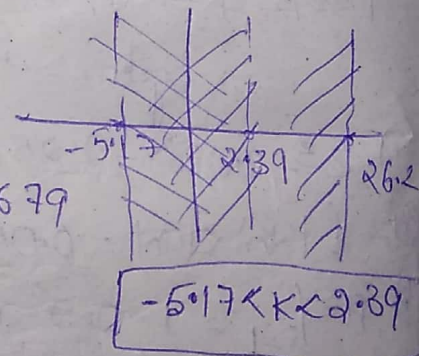
$$1.3679 + 0.2642K < 1$$

$$-1 < 0.3679 + 0.2642K < 1$$

$$-1.3679 < 0.2642K < 1 - 0.3679$$

$$-5.17 < K < 2.39$$

$$K < 2.39, K > -5.17$$



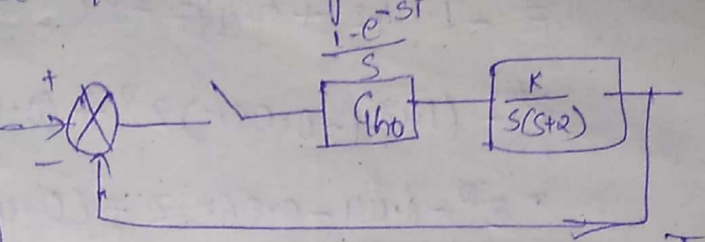
$$\begin{aligned} \text{iii } P(z)|_{z=1} &= P(1) = 1 - 1.3679 + 0.3679K + 0.3679 + 0.2642K \\ &= 0.85K > 0 \Rightarrow K > 0 \end{aligned}$$

$$\begin{aligned} \text{iv } P(z)|_{z=-1} &= P(-1) = 1 + 1.8679 - 0.3679K + 0.3679 + 0.2642K \\ &= 2.0735 - 0.1037K > 0 \end{aligned}$$

$$\boxed{K < 26.02}$$

⑦ Consider the sample data system shown in fig. assume the sampling period is 0.4 sec. find the range of K so that the closed loop system is

Stable $G(z) = z \left[\frac{1-e^{-sT}}{s} \cdot \frac{K}{s(s+2)} \right]$



$$= (1-z^{-1}) z \left\{ \frac{K}{s^2(s+2)} \right\} \quad \left[\because z \left[\frac{1-e^{-sT}}{s} G(s) \right] = (1-z^{-1}) z \left[\frac{G(s)}{s} \right] \right]$$

$$\frac{1}{s^2(s+2)} = \frac{-1/4}{s} + \frac{1/2}{s^2} + \frac{1/4}{s+2}$$

$$\mathcal{L}^{-1} \left(\frac{1}{s^2(s+2)} \right) = -\frac{1}{4} u(t) + \frac{1}{2} t + \frac{1}{4} e^{-2t}$$

$$= -\frac{1}{4} u(kT) + \frac{1}{2} kT + \frac{1}{4} e^{-2kT}$$

$$z \left[\frac{1}{s^2(s+2)} \right] = -\frac{1}{4} \frac{z}{z-1} + \frac{1}{8} T \left(\frac{z}{z-1} \right)^2 + \frac{1}{4} \frac{z}{z-e^{-2T}}$$

$$= -\frac{1}{4} \frac{z}{z-1} + \frac{1}{2} (0.4) \left(\frac{z}{z-1} \right)^2 + \frac{1}{4} \frac{z}{z-e^{-0.8}}$$

$$= \frac{-\frac{1}{4} [z^2(z-1)(z-0.44)] + 0.2 z^2 (z-0.44) + \frac{1}{4} z(z)^2}{(z-1)^2(z-0.44)}$$

$$= \frac{-\frac{1}{4} [z^3 - 1.44z^2 + 0.44z] + 0.2 [z^3 - 0.44z] + \frac{1}{4} [z^3 - 2z^2 + z]}{(z-1)^2(z-0.44)}$$

$$= \frac{z^2 \left[\frac{1.44}{4} + 0.2 - \frac{1}{2} \right] + z \left[\frac{-0.44}{4} - 0.88 + \frac{1}{4} \right]}{(z-1)^2(z-0.44)}$$

$$= \frac{0.06z^2 - 0.74z}{(z-1)^2(z-0.44)}$$

$$G(z) = \frac{K(0.06z^2 - 0.74z)}{(z-1)^2(z-0.44)}$$

$$G(z)_{\text{cl}} = \frac{z-1}{z} \cdot \frac{K(0.06z^2 - 0.74z)}{(z-1)^2(z-0.44)}$$

$$= \frac{K(0.06z^2 - 0.74z)}{z(z-1)(z-0.44)}$$

$$1 + G(z)H(z) = 0 \Rightarrow z(z-1)(z-0.44) + K(0.06z^2 - 0.74z) = 0$$

$$z^3 - 1.44z^2 + 0.44z + K(0.06z^2 - 0.74z) = 0$$

$$z^3 - (1.44 - 0.06K)z^2 + (0.44 - 0.74K)z = 0$$

$$z^2 - (1.44 - 0.06K)z + (0.44 - 0.74K) = 0$$

$$-0.756 < K < 0$$

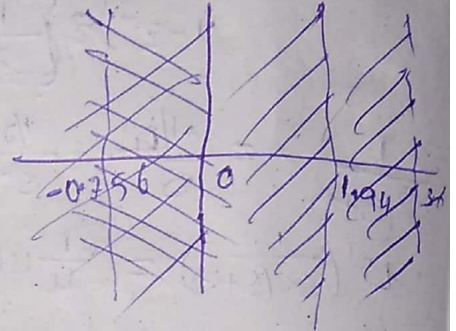
$$|a_2| < |a_0|$$

$$|0.44 - 0.74K| < 1$$

$$-1 < 0.44 - 0.74K < 1$$

$$-1.44 < -0.74K < 0.36$$

$$1.94 > K > -0.756$$



$$P(0) > 0 \Rightarrow 1 - (1.44 - 0.06K) + (0.44 - 0.74K) > 0 \Rightarrow -0.68 > 0$$

$$K < 0$$

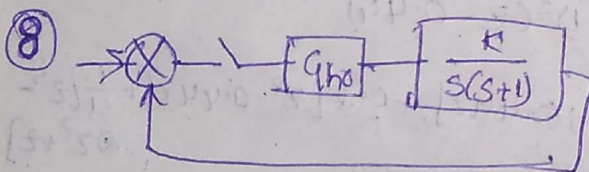
$$P(-1) > 0 \Rightarrow +1 + (1.44 - 0.06K) + (0.44 - 0.74K) > 0$$

$$+2.88 - 0.8K > 0$$

$$-0.8K > -2.88$$

$$K < 3.6$$

$$K < 3.6$$



$$G(z) = z \left[\frac{1 - e^{-sT}}{s} \cdot \frac{K}{s(s+1)} \right]$$

$$= 1 - z^{-1} \cdot z \left[\frac{K}{s^2(s+1)} \right]$$

$$\frac{1}{s^2(s+1)} = \frac{A}{s} + \frac{B}{s^2} + \frac{C}{s+1} = A(s+1) + B(s+1) + Cs^2$$

$$0 = As^2 + A + Bs + B \text{ put } s = -1 \Rightarrow 1 = C$$

$$A + C = 0 \Rightarrow A = -1, A + B = 0 \Rightarrow B = 1$$

$$\frac{1}{s^2(s+1)} = -\frac{1}{s} + \frac{1}{s^2} + \frac{1}{s+1}$$

$$e^{-t} \left[\frac{1}{s^2(s+1)} \right] = -u(t) + t + e^{-t}$$

$$= -u(KT) + KT + e^{-KT}$$

$$z \left[\frac{1}{z^2(z+1)} \right] = -\frac{z}{z-1} + 7 \cdot \left(\frac{z}{z-1} \right)^2 + \frac{z}{z-0.818}$$

$$= -\frac{z}{z-1} + (0.2) \left(\frac{z}{z-1} \right)^2 + \frac{z}{z-0.818}$$

$$= -z(z-1)(z-0.818) + (0.2)z(z-0.818) + z(z-1)$$

$$-z^3 + 0.818z^2 + z^2 - 0.818z - (z^3 - 0.818z^2 - z^2 + 0.818z) + 0.2z^2 - 0.1636z + z^3 - 2z^2 + z$$

$$= \frac{(z-1)^2(z-0.818)}{(z-1)^2(z-0.818)}$$

$$= \frac{z^2(0.818+1+0.2-2) + z(-0.818-0.1636+1)}{(z-1)^2(z-0.818)}$$

$$q(z) = \frac{0.018z^2 + 0.019z}{(z-1)^2(z-0.818)}$$

$$= \frac{z-1}{z} \cdot \frac{0.018z^2 + 0.019z}{(z-1)^2(z-0.818)}$$

$$q(z) = \frac{0.018z^2 + 0.019z}{z(z-1)(z-0.818)}$$

$$1 + q(z)h(z) = 0$$

$$z(z-1)(z-0.818) + K(0.018z^2 + 0.019z) = 0$$

$$z^3 - 0.818z^2 - z^2 + 0.818z + K0.018z^2 + 0.019Kz = 0$$

$$z^3 - (0.818 + 0.018K)z^2 + (0.818 + 0.019K)z = 0$$

$$z^2 - (0.818 + 0.018K)z + (0.818 + 0.019K) = 0$$

$$|K| < |K_0|$$

$$p(0) > 0$$

$$|0.818 + 0.019K| < 1$$

$$1 - (0.818 + 0.018K) + (0.818 + 0.019K) > 0$$

$$-1 < 0.818 + 0.019K < 1$$

$$K - 0.818 + 0.018K + 0.818 + 0.019K > 0$$

$$-0.818 < 0.019K < 0.182$$

$$0.037K > 0 \Rightarrow K > 0$$

$$-0.668 < K < 9.57$$

$$p(0) > 0$$

$$-0.668 > K > -9.57$$

$$1 + 1.818 - 0.018K + 0.818 + 0.019K > 0$$

$$0.001K > -3.636 \Rightarrow K > -3636$$